



# CHARACTERISTICS OF WORK

Characteristics	Symbol	Min.	Tip	Max	Units	Pays attention
Pressure range	$P_{OP}$	0	-	50	kPa	1.0 kPa = 0.145 psi
Supply voltage	$V_S$	-	10	16	Vdc	The device is ratiometric within ra
Current	$I_o$	-	6.0	-	mAdc	The use of the device over the range an
Full scale Span	$V_{FSS}$	38,5	40	41,5	mV	additional mistake because of their own
Offset	$V_{off}$	-1,0	-	1,0	mV	heatingt.
Sensitivity	AV/AP	-	0,8	-	mV/kPa	specified can induce ment specified
Linearity	-	-0,25	-	0,25	% $V_{FSS}$	
Hysteresis of the pressure	-	-	+0,1	-	% $V_{FSS}$	de 0 a 50 kPa
Temperature hysteresis	-	-	+0,5	-	% $V_{FSS}$	de 40°C a 125°C
Effect of temperature on the Span	$TCV_{FSS}$	-1,0	-	1,0	% $V_{FSS}$	
Effect of temperature on the offset	$TCV_{off}$	-1,00	-	1,00	% $V_{FSS}$	
Input impedance	$Z_{in}$	1000	-	2500	$\Omega$	
Output Impedance	$Z_{out}$	1400	-	3000	$\Omega$	
Activation Time	$t_R$	-	1,0	-	ms	
Heating (Warm-Up)	-	-	20	-	ms	
Offset Stability	-	-	+0,5	-	% $V_{FSS}$	

(1).  $V_S = 10$  Vds,  $T_A = 25^\circ\text{C}$ , unless otherwise stated,  $P1 > P2$

## MAXIMUM VALUES (1)

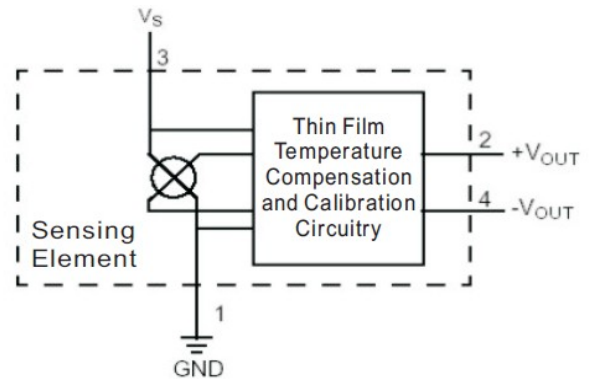
Characteristics	Symbol	Value	Units
Maximum pressure	$P_{max}$	200	kPa
Storage temperature	$T_{stg}$	-40 a 125	$^\circ\text{C}$
Working temperature	$T_A$	-40 a 125	$^\circ\text{C}$

(1). Exposure beyond the specified limits may cause permanent damage or degradation of the device

## Block diagram of the internal circuitry on the stand-alone pressure sensor chip

### Voltage Output versus Applied Differential Pressure

The output voltage of the gauge sensor increases with increasing pressure applied to the pressure side (P1) relative to the vacuum side (P2). Similarly, output voltage increases as increasing vacuum is applied to the vacuum side (P2) relative to the pressure side (P1).



## Linearity

Linearity refers to how well a transducer's output follows the equation:  $V_{out} = V_{off} + \text{sensitivity} \times P$  over the operating pressure range. There are two basic methods for calculating nonlinearity: (1) end point straight line fit (see Figure 2 ) or (2) a least squares best line fit. While a least squares fit gives the "best case" linearity error (lower numerical value), the calculations required are burdensome. Conversely, an end point fit will give the "worst case" error (often more desirable in error budget calculations) and the calculations are more straightforward for the user. Motorola's specified pressure sensor linearities are based on the end point straight line method measured at the midrange pressure

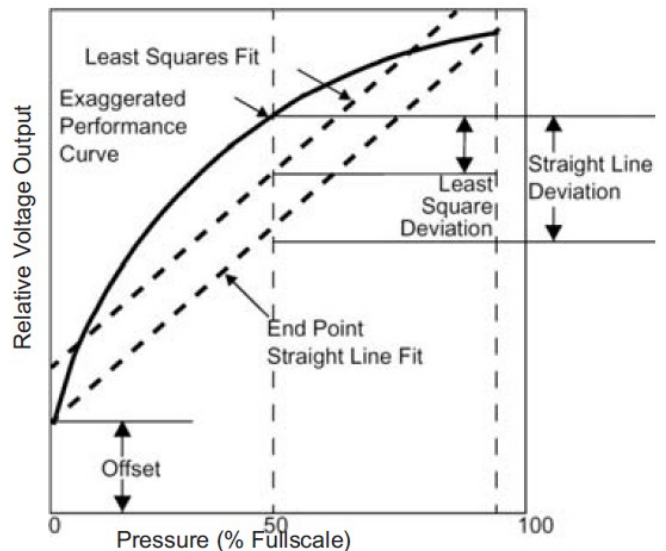
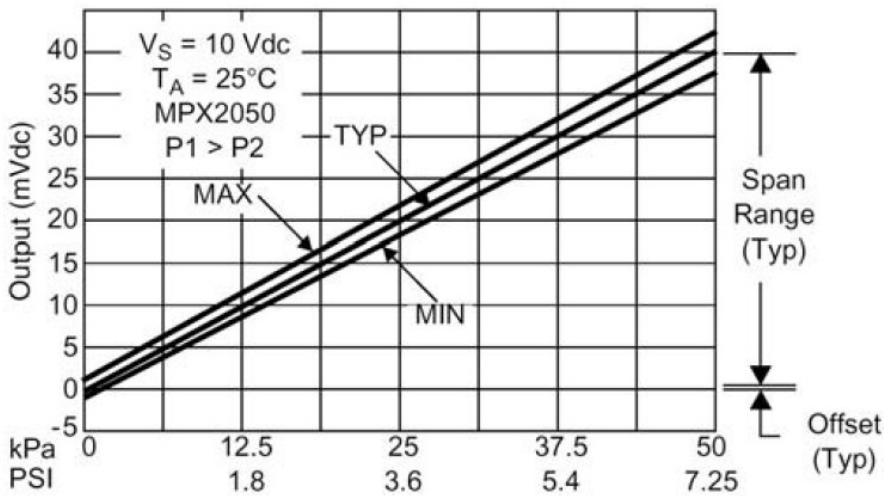


Figure 2. Linearity Specification Comparison

## On-Chip Temperature Compensation and Calibration

Figure 3 shows the minimum, maximum and typical output characteristics of the MPX2050 series at 25°C. The output is directly proportional to the differential pressure and is essentially a straight line.

The effects of temperature on Full-Scale Span and Offset are very small and are shown under Operating Characteristics.



**Figure 3. Output versus Pressure Differential**

**Figure 4. Cross-Sectional Diagram (not to scale)**

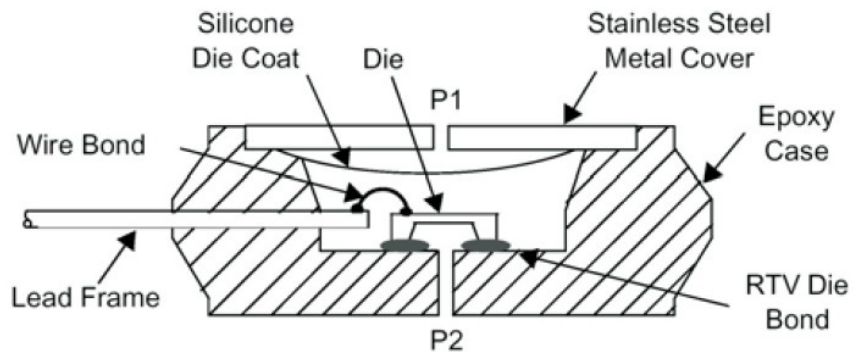


Figure 4 illustrates the differential or gauge configuration in the basic chip carrier (Case 344). A silicone gel isolates the die surface and wire bonds from the environment, while allowing the pressure signal to be transmitted to the silicon diaphragm.

This series pressure sensor operating characteristics and internal reliability and qualification tests are based on use of dry air as the pressure media. Media other than dry air may have adverse effects on sensor performance and long term reliability. Contact the factory for information regarding media compatibility in your application.